

DescriptionAxial impeller with enhanced flow.Technical Field

This invention concerns an axial impeller with enhanced flow equipped with blades that are inclined in the plane of rotation of 5 the impeller and a hub having small dimensions.

Background Art

The impeller according to the present invention may be used for 10 various applications, for example, for moving air through a heat exchanger or radiator of an engine cooling system for a vehicle or similar apparatus; or for moving air through a heat exchanger for heating equipment and/or through air conditioning evaporators used in vehicle cabins.

Furthermore, the impeller according to the present invention 15 may be used to move air in fixed air conditioning or heating equipment in homes.

Impellers of this type must meet various requirements, including: low noise, high efficiency, compact size, ability to achieve good head (or pressure) values and flow.

20 In order obtain a good flow of air by using impellers whose dimensions are small, it may be necessary to extend the blades towards the centre of the impeller itself, thereby increasing the flow in the central portion.

An impeller of this type is described in United States patent 25 No. 6,126,395; its compact impeller features an extension of the blades towards the centre of the impeller, the blades are connected and overlap a hub.

The latter presents a curved area containing the stator of the 30 actuator motor, while each blade contains a permanent magnet that works with the stator in order to create the torque necessary for rotation.

Due to the structure of the hub surrounding the stator it is difficult to change the type and size of the motor that rotationally drives the impeller.

Depending on the type of application and in order to obtain the best performance, it may be necessary to fit impellers of a certain size with electric motors of different sizes and power ratings.

5 In particular, to meet standardization requirements, it may be necessary to use motors with diameters that are relatively wide on impellers that are compact in size.

#### Disclosure of the Invention

10 One aim of the present invention is to produce an impeller that features enhanced air flow, whose overall dimensions are generally small.

According to one aspect, the present invention provides an axial impeller as defined in claim 1.

15 The dependent claims refer to preferred, advantageous embodiments of the invention.

#### Description of the Drawings

20 The accompanying drawings illustrate an embodiment of the present invention without limiting the scope of its application, in which:

- figure 1 shows a front view of the impeller according to the present invention;

- figure 2 shows a sectional view of the impeller of figure 1;

25 - figure 3 shows a perspective view of the impeller shown in the previous figures;

- figure 3a shows a perspective view of a detail of a variation of the impeller according to the present invention;

- figure 4 shows a schematic front view of a blade of the impeller shown in the previous figures;

30 - figure 5 shows a sectional view of some of the profiles taken at different widths of the impeller;

- figure 6 shows a sectional view of a profile and its respective geometric features;

35 - figure 7 shows a front view of a second embodiment of the impeller of figure 1;

- figure 8 shows a lateral view of the impeller of figure 7;

- figure 9 shows a perspective view of the impeller of figure 7;
- figure 10 shows a front view of a third embodiment of the impeller of figure 1;
- 5 - figure 11 shows a lateral view of the impeller of figure 10;
- figure 12 shows a perspective view of the impeller of figure 10.

Detailed Description of the Preferred Embodiments of the Invention

10 As shown in the accompanying drawings, the impeller 1 turns about an axis 2, in a plane XY, and comprises a central hub 3 with diameter D1 to which a plurality of blades 4 are attached, which are curved in the plane XY of rotation of the impeller 1.

15 The impeller 1 is driven by an electric motor 3a, having a diameter D2, which in general is different from the diameter D1 of the hub 3 and, more specifically, the motor 3a has a diameter D2 that is greater than the diameter D1 of the hub 3, as a result of which the blades 4 overlap the motor 3a.

20 The blades 4 have a base 5, a tip 6 and are delimited by a concave leading edge 7 and a convex trailing edge 8.

25 In order to achieve the best results in terms of efficiency, flow and air pressure, the invention specifies that the impeller 1 should rotate in accordance with direction of rotation V, shown in figures 1 and 4, so that the tip 6 of each blade 4 meets the airflow prior to the base 5.

30 Figure 4 shows an example of the geometric features of a blade 4: the leading and trailing edges 7, 8 are each delimited by two circular arc segments 9, 10 and 11, 12, respectively, having a radius R1 and R2, at which the one arc segment changes to the other arc segment having a different radius.

In the example of figure 4, the general dimensions of a blade 4 projected onto the plane XY are shown in table 1 below:

Table 1 - Dimensions of a blade 4

	Internal segment radius (mm)	Change radius (mm)	External segment radius (mm)
Leading edge (Ref. 7)	50.5 (Ref. 9)	61.6 (Ref. R1)	45.3 (Ref. 10)

Trailing edge (Ref. 8)	29.3 (Ref. 11)	49.9 (Ref. R2)	46.4 (Ref. 12)
---------------------------	-------------------	-------------------	-------------------

The general geometric features of the blade 4 are defined in relation to a theoretical hub of 55 mm in diameter, that is, the blade 4, has a minimum radius of  $R_{min}=27.5$  mm at base 5, and an external diameter of 190 mm, that is, it has a maximum radius of 5  $R_{max}=95$  mm at the tip 6, and as a result the blade 4 has a theoretical radial extension of 67.5 mm

As will be seen below, the hub 3 may have a different size, that is, it may be larger, in which case the blade 4 will be truncated at the effective diameter of the hub 3.

10 Since the blade 4 has a minimum radius of  $R_{min}=27.5$  mm and a maximum radius of  $R_{max}=95$  mm, then, for the leading edge 7, the radius  $R_1$  at which a change of circular arc occurs corresponds to approximately half (or 50%) of the radial extension of the leading edge 7, that is, 67.5 mm, as specified above.

15 The portion 9 of the leading edge 7, which is closer to the base 5, is defined by a circular arc with a radius equal to approximately 53% of the radius  $R_{max}$ , and the portion 10 of the leading edge 7, closer to the tip 6, is defined by a circular arc segment with a radius equal to approximately 47% of the radius  $R_{max}$  20 of the blade 4.

For the trailing edge 8, the radius  $R_2$  at which the change in the circular arc occurs is approximately one third (or 33%) of the radial extension of the leading edge, namely 67.5 mm

25 The portion 11 of the trailing edge 8, closer to the base 5, is defined by an arc with a radius equal to approximately 30% of the radius  $R_{max}$  of the blade 4; the portion 12 of the trailing edge 8, closer to the tip 6, is defined by an arc with a radius equal to approximately 49% of the radius  $R_{max}$  of the blade 4.

The dimensions as percentages are shown in table 2 below:

30

Table 2 - Dimensions of a blade 4 as percentages

	Internal segment radius (% of $R_{max}$ )	Change radius (% of blade extension = $R_{max}-R_{min}$ )	External segment radius (% of $R_{max}$ )
Leading edge (Ref. 7)	53 (Ref. 9)	50 (Ref. R1)	47 (Ref. 10)

Trailing edge (Ref. 8)	30 (Ref. 11)	33 (Ref. R2)	49 (Ref. 12)
---------------------------	-----------------	-----------------	-----------------

Satisfactory results were achieved in terms of flow, pressure and noise, even with values around these percentage dimensions. In particular, in accordance with the information set out above in percentage terms, it would be possible to achieve variations of plus or minus 10% of the dimensions indicated above.

The percentage ranges in relation to the dimensions are shown in table 3 below:

Table 3 - Percentage ranges for the edges of a blade 4

	Internal segment radius (% of Rmax)	Change radius (% of blade extension = % of Rmax-Rmin)	External segment radius (% of Rmax)
Leading edge (Ref. 7)	47.7- 58.3 (Ref. 9)	45-55 (Ref. R1)	42.3- 51.7 (Ref. 10)
Trailing edge (Ref. 8)	27-33 (Ref. 11)	29.7- 36.3 (Ref. R2)	44.1- 53.9 (Ref. 12)

For the edges 7, 8 of the blade 4 in the area of the change in the circular arc, an appropriate connection may be provided so that the curve formed by the two edges 7, 8 is smooth and without cusps.

As regards the angular extension or width of the blades, again with reference to figure 4, the projection of the blade 4 onto the plane XY 5 makes, at the base 5, an angle B1 of approximately 41 degrees at the centre and, at the tip, an angle B2 of approximately 37 degrees at the centre.

In this case as well, satisfactory results were obtained in terms of flow, pressure and noise, with values for angles B1, B2 around these values. In particular, it would be possible to achieve variations of plus or minus 10% of these angles; thus, angle B1 may vary from 36.9 to 45.1 degrees while angle B2 may vary from 33.3 to 40.7 degrees.

In general, in view of the plastic material from which impellers are made, all of the dimensions and angles may vary by plus or minus 5% of the indicated values.

Considering the respective bisectors of angles B1, B2 and following the direction of rotation V of impeller 1, the tip 6 leads the base 5 by an angle B3 of approximately 21 degrees.

Other angles that are a feature of the blade 4 are angles B4, B5, B6, B7 (figure 4) formed by the respective tangents to the two

edges 7, 8 and by the respective radii issuing from the centre of the impeller and passing through points S, T, N, M: the angles B4 and B5 are respectively 25 and 54 degrees and the angles B6, B7 are respectively 22 and 52 degrees.

5 There may be between four and nine blades 4 and, in accordance with the preferred embodiment, there are seven blades 4 arranged in accordance with differing angles.

The angles between one blade and the next - considering for example the corresponding leading edge 7 or trailing edge 8 - are: 10 50.7; 106.0; 156.5; 205.2; 257.5; 312.9 (in degrees).

Using these angles provides an advantage with regard to noise, while the impeller 1 remains completely balanced both statically and dynamically.

15 Each blade 4 is made of a series of aerodynamic profiles that are connected progressively starting from the base 5 to the tip 6.

Figure 5 shows seven profiles 13-19, that relate to respective sections taken at various intervals along the radial extension of a blade 4.

20 Profiles 13-19 are also defined by the geometric features exemplified in figure 6 for one of the profiles. As shown in figure 6, each profile 13-19 has a centre line L1 that forms a smooth curve, without flexes or cusps, and a chord L2.

25 Each profile 13-19 is furthermore characterized by two angles of incidence BLE, BTE at the leading edge and at the trailing edge, and these angles are formed by their respective tangents to the centre line L1 at the point of intersection with the leading edge and with the trailing edge and a respective straight line perpendicular to the plane XY through the corresponding intersection points.

30 Table 4 below shows, with reference to the seven profiles 13-19, the angles of leading edge BLE and of trailing edge BTE, the length of the centre line L1 and of the chord L2 of the profiles of a blade 4.

35 **Table 4 - Radial position, leading and trailing edge angles, centre line length and chord of blade 4 profiles**

Profile	Extension %	Radius (mm)	BLE (degrees)	BTE (degrees)	L1 (centre line mm)	L2 (chord mm)
13	0	27.5	65	20	30.40	29.24

14	19.44	40.6	72	30	36.96	35.88
15	37.68	52.9	75	42	41.86	41.09
16	55.89	65.2	77.5	50.5	47.04	46.43
17	72.59	76.5	80.58	56.27	53.50	52.88
18	88.35	87.1	79.34	62.02	59.30	59.13
19	1	95	73.73	72.55	62.51	62.5

It should be noted that the thickness of each profile 13-19, in accordance with the typical shape of wing profiles, initially increases, and reaches a maximum value of S-MAX at around 20% of the length of the centre line L1, and from there progressively decreases up to the trailing edge 8.

In percentage terms, the thickness S-MAX lies between 2.26% and 2.42% of the radius Rmax; the thickness of the profiles is distributed symmetrically about the centre line L1.

The positions of profiles 13-19 relative to the radial extension of a blade 4 and the respective values of the thickness in relation to their position with respect to the centre line L1 are shown in table 5 below.

Table 5 - Radial position and thickness values of blade 4 profiles

Profile	Extension %	Radius (mm)	Thickness						
			S-Max (mm)	dimensionless in relation to S-MAX					
				0% L1	20% L1	40% L1	60% L1	80% L1	100% L1
13	0	27.5	2.18	0.569196	1	0.846665	0.719688	0.591336	0.109558
14	19.44	40.6	2.23	0.600601	1	0.89373	0.763659	0.623011	0.126933
15	37.68	52.9	2.23	0.69237	1	0.973294	0.816338	0.664273	0.172666
16	55.89	65.2	2.25	0.694791	1	0.934996	0.817809	0.667854	0.179252
17	72.59	76.5	2.26	0.697084	1	0.935484	0.819178	0.671675	0.185418
18	88.35	87.1	2.30	0.702375	1	0.936645	0.822311	0.673064	0.199574
19	1	95	2.15	0.731532	1	0.913833	0.777364	0.624127	0.168607

Table 6 below shows the actual thickness values in mm in relation to their position relative to the centre line L1 for each profile 13-19 referring to the embodiment illustrated in the drawings.

Table 6 - Thickness values in mm of profiles 13-19 of a blade 4

Profile	Thickness (mm)					
	0% L1	20% L1	40% L1	60% L1	80% L1	100% L1
13	1.24	2.18	1.85	1.57	1.29	0.24

14	1.34	2.23	1.99	1.70	1.39	0.28
15	1.54	2.23	2.17	1.82	1.48	0.38
16	1.56	2.25	2.10	1.84	1.50	0.40
17	1.58	2.26	2.12	1.85	1.52	0.42
18	1.62	2.30	2.16	1.89	1.55	0.46
19	1.57	2.15	1.96	1.67	1.34	0.36

Preferably, profiles 13-19 are delimited by an elliptical connection, on the side of the leading edge 7, and by a truncation effected by a straight segment, on the side of the trailing edge 8.

As indicated previously, important features of the impeller 1  
5 in accordance with this invention are provided by hub 3. The latter has a limited thickness and a diameter that is smaller than the diameter of motor 3a.

Between the hub 3 and each blade 4 there is also a box-shaped portion 20 which provides a connection, at least partially, between  
10 the hub 3 and each blade 4. For example, in the case illustrated in the drawings seven box-shaped portions 20 are shown, that is to say, the same number of portions as there are blades 4, which in turn are partially and directly attached to the hub 3 in the area near the leading edge 7.

15 The portions 20 match the external shape of the electric motor 3a and in general provide a seat 21 for the latter. The electric motor 3a is therefore partially contained within this seat 21 and accordingly it can be larger than the hub 3.

20 The seat 21 has a diameter that is slightly greater than the diameter D2 of the motor 3a in order to allow the impeller 1 to rotate and also to accommodate motors whose diameters are slightly different.

25 It should be noted that, because the hub 3 is discoidal and the blades 4 have an angle of incidence at the base 5 that is relatively high, in the part near the trailing edge 8, the blades 4, cannot be attached directly to the hub 3.

30 In fact, the part near the trailing edge 8 is located in a position that is axially shifted with respect to the hub disk 3. The box-shaped portions 20 therefore enable a connection to be made between the hub 3 and the proximate part of the trailing edge 8 of the blades 4 and also to achieve a certain degree of stiffening of the blade 4 in the base 5.

In accordance with a variation of the invention shown in figure 3a, the impeller 1 has a discoidal hub 3 and a portion 20a, whose only function is to stiffen and connect the blade portions, proximate to the trailing edge 8, which is located in a position 5 that is axially shifted with respect to the hub disk 3.

In this embodiment, the portion 20a does not specifically define a seat for the electric motor, which may have dimensions (in particular the diameter) that are comparable or smaller than those of the hub 3.

10 There is however, an increase in the airflow generated by the blades 4, because the discoidal shape of the hub 3 causes an increase in the section through which the airflow passes compared to a traditional solution in which the hub is equipped with a lateral skirt.

15 In the examples that are illustrated, the hub 3 has a diameter D1 of 75 mm, while the motor 3a has a diameter D2 of 100 mm

The seat 21 has a diameter of approximately 105 mm in order to accommodate the motor 3a. Considering the data provided above, with regard to the blade 4, the latter is truncated at the base 5 to a 20 diameter D1 of 75 mm, that is, to a radius of 37.5 mm, and, in the proximate part of the trailing edge 8, it is furthermore partially replaced by the portion 20.

25 Although the motor 3a overlaps the proximate part of the leading edge 7, it contributes to enhancing the airflow created by the impeller 1 and performance in general.

In the second and third embodiments, shown in figures 7, 8, 9, 10, 11 and 12, the impeller 1 is also equipped with a ring 22 which 30 is coaxial to the axis 2 of rotation and attached to the tip 6 of each blade 4. The ring 22 is defined by a cylindrical wall having a circular section, which is parallel to the axis 2 of rotation and has an internal area 23 that is integral with the tips 6 of the blades 4. The main function of the ring 22 is to stiffen the blades 6, in order to limit their distortion caused by the centrifugal and aerodynamic forces. The ring 22 also makes it possible to guide the 35 airflow through the disc defined by the blades 6 in a way that increases the efficiency of the impeller 1.

The third embodiment in figures 10-12 is further equipped with a frame 24 attached to the edge of the ring 22 and extending radially away from the axis 2 of rotation. The frame has an outer portion which lies in a plane at right angles to the aforementioned 5 axis 2 of rotation. Since the impeller 1 is usually mounted in an appropriate opening, located in a fixed support wall, the frame 24, which overlaps the wall, makes it possible to contain the airflow that passes outside the disk of the blades 6, between the blades 6 themselves and the internal edge of the aforementioned opening, in 10 order to further improve the head values that can be achieved.

The impeller provided by this invention achieves numerous advantages.

As previously indicated, the discoidal shape without a lateral skirt of hub 3 causes an increase in the section through which the 15 airflow passes and accordingly an increase in the flow itself.

Furthermore, even the blades that extend towards the centre of the impeller increase the airflow.

The seat created by the box-shaped portions 20 allows electric 20 motors of a larger diameter to be fitted, and in particular it is possible to fit larger electric motors that provide a greater torque.

Accordingly it is possible to find the correct coupling between the impeller and electric motor, using an existing electric motor that generates the torque necessary for a certain type of impeller.

25 In this way it is possible to avoid the necessity of designing a new electric motor adapted in size to fit the impeller hub.

Furthermore, the lack of a lateral skirt in the hub and the extension of the blades towards the centre of the impeller, promotes the cooling of the electric motor.

30 The invention as described above may be modified and varied without departing from the scope of the inventive concept is defined in the claims.

LIST OF REFERENCE CHARACTERS	
Reference	Description
1	Axial impeller
2	Axis of rotation
3	Central hub
3a	Electric motor
4	Impeller blade 1
5	Base of blade 4
6	Tip of blade 4
7	Concave leading edge
8	Convex trailing edge
9	Internal arc segment of 7
10	External arc segment of 7
11	Internal arc segment of 8
12	External arc segment of 8
13-19	Aerodynamic profiles
20	Box-shaped portion
20a	Stiffening portion
21	Seat for motor 3a
22	Ring
23	Internal surface of ring
24	Frame of ring
XY	Plane of rotation
V	Direction of rotation
R1	Radius of change of segments 9 and 10
R2	Radius of change of segments 11 and 12
XY	Projection in plane
B1 - B7	Characteristic angles of blade 4
M, N, S, T	Characteristic points of blade 4
L1	Centre line
L2	Chord
BLE	Angles of incidence at leading edge
BTE	Angles of incidence at trailing edge
D1	Diameter of hub 3
D2	Diameter of motor 3
Rmin	Theoretical hub radius
Rmax	External impeller radius